

MEASUREMENT DATA FOR IMPROVING ITU-R RECOMMENDATION P.1812

Database of filtered measurement records

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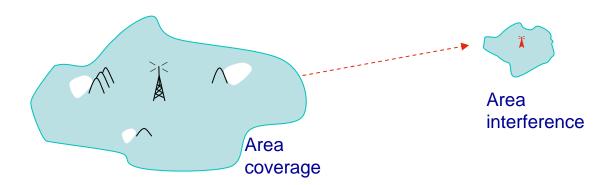
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Background

ITU-R Recommendation P.1812

 A path-specific propagation prediction method for point-to-area terrestrial services operating up to 3GHz



- A new recommendation first published in 2007
- The SG3 work plan aims to improve the accuracy of this model

A new database of terrestrial propagation measurements has recently been assembled within ITU-R SG3

Ideal for testing the aforementioned recommendation



Rationale

The new database of measurements has proved very useful but:

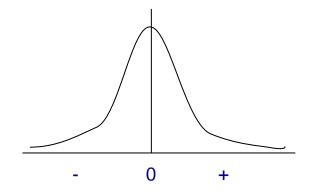
- Inevitably a large measurement database will contain some errors
 - The difference between a prediction and a measurement depends on both model and measurement errors
- Not all of the data within the database is of equal weight. For example:
 - There are some long term measurements and some point samples
 - There are some height gain measurements which should be used for height gain, but not for path evaluation
- The database is not uniformly distributed over parameter space of the models.
 - Risk of bias if model only matches well to the most numerous measurement set



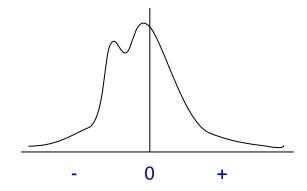
Rationale

In attempting to improve ITU-R P.1812 it became clear differences between models were being obscured by measurement errors

- Some measurements were very clearly in error
 - Line of sight paths with median loss much less than free space (Calibration)
 - Line of sight paths with high excess loss over free space (Clutter)
- The prediction errors were not normally distributed
 - I.E. the errors were not random



Hoped for Error Distribution



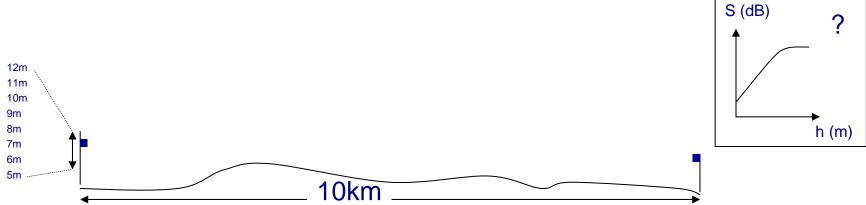
Actual Error Distribution



Rationale

Also

- Some datasets were missing some parameters
 - Clutter information along path profile missing
 - Low resolution terrain profiles especially over sea
 - Missing radioclimatic data and Land/Sea/Coastal information
- The height gain measurements were adding noise to the sampling
 - A lack of associated clutter data meant that many nearly identical paths had large path loss differences





Plan

The measurement database required closer examination and a plan was made:

- Filter the records against a set of rules
 - Flag each record against several criteria
- Which required moving the records into a new database
 - To permit flagging of the data
 - To allow missing data to be filled in where possible
 - To allow new data to be added from new sources.
 - To allow model results to be stored alongside the data records
- And to create an extraction application
 - Permit data to be extracted based on database queries of parameter values
 - Plot and display data and results in a readily usable form
 - To help analyse prediction outliers manually



Data validity

All measurement records were added into the database and then assessed into three categories

- Records thought to be good
- Records with a few minor concerns but otherwise good
 - For example records that were repairable
- Records with major concerns
 - For example
 - Records where the path profile was not monotonic
 - Records with missing vital parameters
 - Records with conflicting information
 - Dummy records designed for model implementation testing

Records falling into the first two are considered suitable for testing

Records were only flagged, none were thrown away



Flagging 1

Two major level flags were applied

- IsValid
 - Records thought to be good (Flagged as 1)
 - Records with a few minor concerns but otherwise good (Flagged as 1)
 - For example records that were repairable
 - Records with major concerns
 - 0 Test links
 - 1 TX, RX location concerns
 - 2 Path profile concerns
 - 3 Clutter concerns depends on our belief in LOS model
 - 4 Duplicate link
 - 5 Calibration concerns depends on our belief in LOS model



Flagging 2

- IsLongTerm
 - Records with many time percentages considered long term (1)
 - Records with none or 50% time considered not long term (0)
 - This is the majority of the data

In addition:

An "RxHeightGainGroup" flag was added to identify height gain tests

and

The highest RX point is a record is flagged with "IsTopRXHeightInGroup"



Flag counts

Field and Value	# Links (Measurements)		
Total	5832 (35840)		
IsValid=0 (test links)		8 (24)	
IsValid=-1 (TX, RX location concerns)		38 (130)	
IsValid=-2 (profile concerns)		32 (104)	
IsValid=-3 (clutter concerns)		341 (3226)	
IsValid=-4 (duplicate link)		19 (27)	
IsValid=-5 (LOS path loss concerns)		21 (823)	
IsValid=1 && IsLongTerm=0 (&& IsWorstMonth=0)	Total	4922 (29061)	
	InputsValid=1	4914 (25309)	
	InputsValid=1 && IsTopRXHeightInGroup=1	4914 (9639)	
	Total	428 (2307)	
IsValid=1 && IsLongTerm=1 && IsWorstMonth=0	InputsValid=1	402 (1410)	
	InputsValid=1 && IsTopRXHeightInGroup=1	402 (1410)	
IsValid=1 && IsWorstMonth=0	InputsValid=1 && IsTopRXHeightInGroup=1	5316 (11049)	

Best set

10



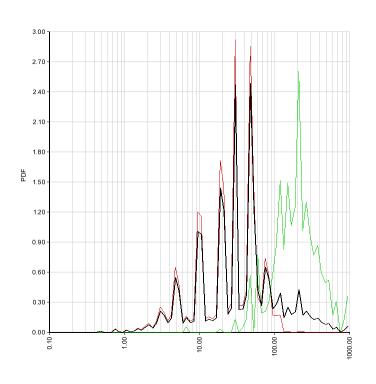
Parameter coverage of the database

(just a few examples)

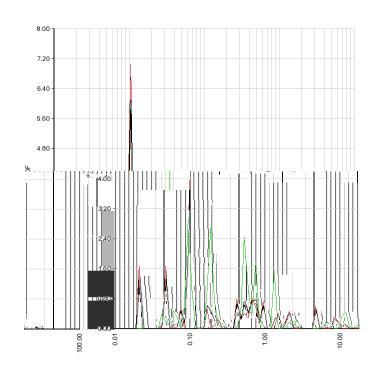


Parameter coverage

 How well are longer and shorter paths and higher and lower frequencies represented?



Path Lengths



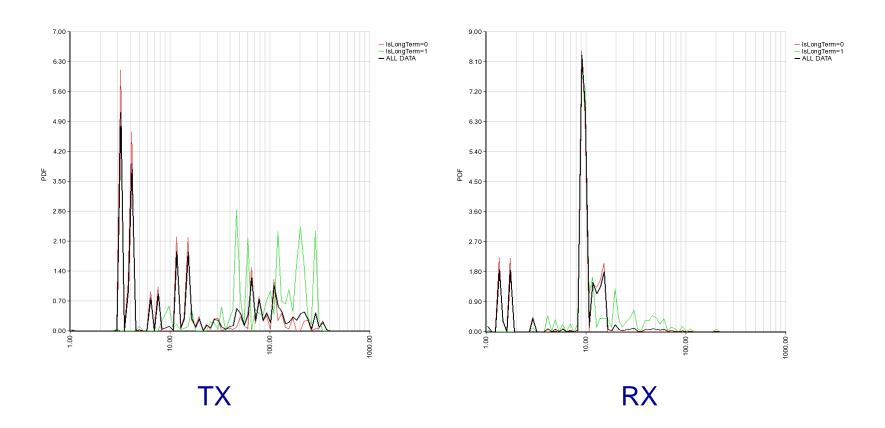
Frequencies

(Green = Long Term data, Red = Short term data, Black = All data) 12



Parameter coverage

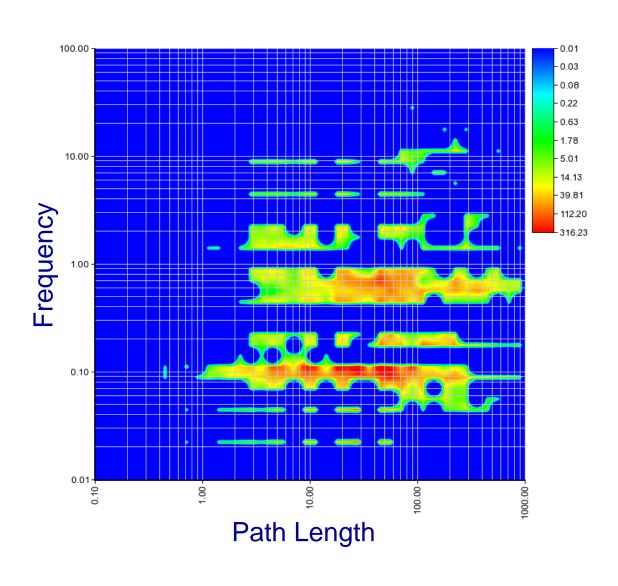
Height above ground



(Green = Long Term data, Red = Short term data, Black = All data) 13



Joint parameter coverage





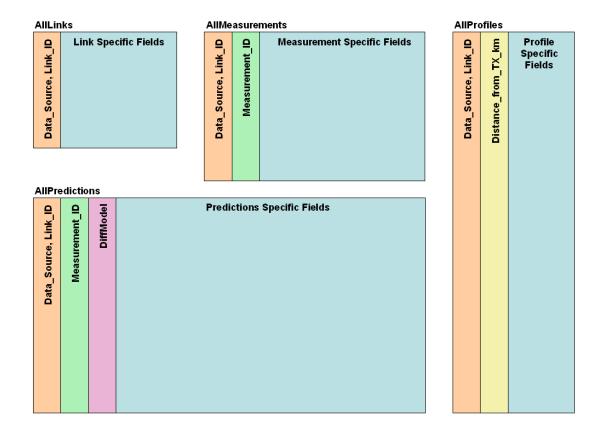
Accessing the data

(and the model results)



SQL Database

Data is stored in an SQL database



Can output data in XML, KML, SG3 CSV



Web access

Link http://www.rcru.rl.ac.uk/njt/linkdatabase/linkdatabase.php

C Display all data sources in database C Display all lanks C Display link info Display link info Display link with name C Display link link T Latistude, deg ** 40.0502 MD TL Leopstude, deg ** -105. 24 MD Display link link T Latistude, deg ** 40.0502 MD TL Leopstude, deg ** -105. 24 MD Display link link T Latistude, deg ** 40.0502 MD TL Leopstude, deg ** -105. 24 MD Display link link T Latistude, deg ** 40.0502 MD TL Leopstude, deg ** -105. 24 MD Display link link T Latistude, deg ** -40.0502 MD TL Leopstude, deg ** -105. 24 MD Display link link T Latistude, deg ** -40.0502 MD TL Leopstude, deg ** -105. 24 MD Display link link T Latistude, deg ** -40.0502 MD TL Leopstude, deg ** -105. 24 MD Display link link T Latistude, deg ** -40.0502 MD TL Leopstude, deg ** -105. 24 MD Display link link T Latistude, deg ** -40.0502 MD TL Leopstude, deg ** -105. 24 MD Display link link T Latistude, deg ** -40.0502 MD TL Leopstude, deg ** -105. 24 MD Display link link T Latistude, deg ** -40.0502 MD TL Leopstude, deg ** -105. 24 MD Display link link T Latistude, deg ** -40.0502 MD TL Leopstude, deg ** -105. 24 MD Display link link link T Latistude, deg ** -40.0502 MD TL Leopstude, deg ** -105. 24 MD Display link link link T Latistude, deg ** -40.0502 MD TL Leopstude, deg ** -40.0502 MD

A javascript application facilitates access via the web interface

Links in to Google maps

Predictions

Go to predictions analysis page

Downloads

Full database in XML or Fryderyk CSV formats - 5540 files

Link data with measurements for top RX heights only in XML or Fryderyk CSV formats - 5540 files.

Link data with separate files for each RX height gain function XML or Fryderyk CSV formats - 6107 files.

XML reader sample code - Note this requires libixml2 DLL.

MinGW compiled ibxml2 DLI, and include files - Note this may not work on your system.



Sample outputs

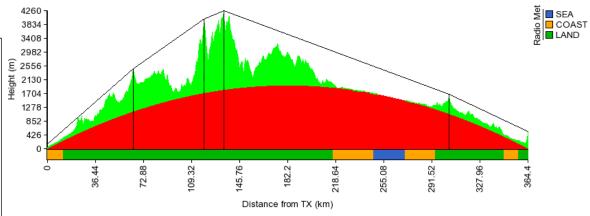
	1	2	3	4	5
Measurement_ID:	0	1	2	3	4
Frequency_GHz:	0.159500	0.159500	0.159500	0.159500	0.159500
TX_AHaG_m:	80.0	80.0	80.0	80.0	80.0
TX_EAHaG_m:					
RX_AHaG_m:	7.0	7.0	7.0	7.0	7.0
Polarization:					
TX_Power_dBm:					
Max_Lb_dB:					
TX_Gain_dBi:					
RX_Gain_dBi:					
RX_AntennaType:					
EIRP_H_dBW:					
EIRP_V_dBW:					
EIRP_Total_dBW:					
HRP_Red_dB:					
TimePercentage:	1.000	10.000	50.000	90.000	99.000
RelativeLossToFS_dB:					
${\sf MeasuredFieldStrength_dBuVperm:}$	-10.9	-17.1	-26.8	-35.2	-42.2
BasicTransmissionLoss_dB:	194.3	200.5	210.2	218.6	225.6
RXHeightGainGroup:	-1	-1	-1	-1	-1
lsTopRXHeightInGroup:	1	1	1	1	1

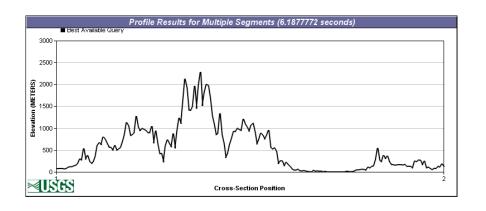
Profile Points: 366 found TX-RX Distance (km): 364.4

Terrain Height Range (m): [-9.0-2444.0]

Max Clutter Height (m): 0.0 Clutter Categories: present

Radio Met Categories: present

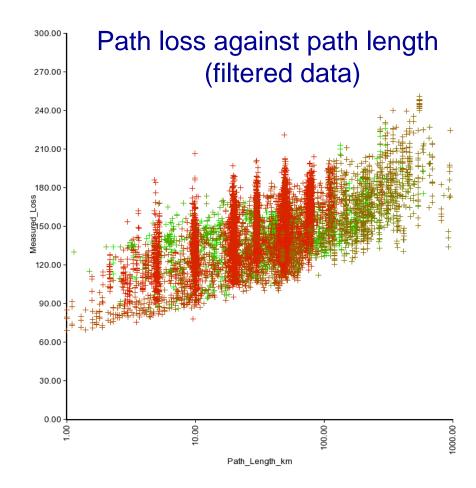






Data analysis

X Data:	© Suggested: Lb C Custom:	_
Y Data:	© Suggested: PredictionError C Custorn:	
Group data nto sets by:	Suggested: None C Custom:	(applicable for Scatter, PDF and CDF plots)
SQL data constraint	© Presets: 3pt Deygout Model Only Set below ○ Custom:	(SQLite expression syntax)
Number of bin	s: 50	(applicable for PDF, CDF and 2D PDF plots)
Display key:		piotoj
Display grid:		
Display statist	ics:	
Display X=Y lii	ne: 🗆	(applicable for Scatter plot)
Marker style:	cross 💌	(applicable for Scatter plot)
Marker size (pixels):	4	(applicable for Scatter plot)
X-axis size (pixels):	600	
Y-axis size [pixels]:	000	
Number of tick X-axis:		
Number of tick Y-axis:	s on 111	
X-axis	• Automatic	
minimum:	0	
X-axis	 Automatic 	



http://www.rcru.rl.ac.uk/njt/linkdatabase/linkdatabase_predictions.php



Displaying model results

Typical prediction analysis data extraction filter:

DiffModel==1 AND IsTopRXHeightInGroup==1 AND IsValid==1 AND IsWorstMonth==0 AND InputsValid==1

Field and Value	Diffraction Model
DiffModel=1	3-edge Deygout model as in ITU-R P.1812
DiffModel=3	Bullington model with LOS taper
DiffModel=5	3-edge Deygout model as in ITU-R P.1812 with some aspects of the US PTP cylindrical edge model
DiffModel=6	3-edge Deygout model as in ITU-R P.1812 with Chinese spherical Earth proposal detailed in ITU document 3K/150-E
DiffModel=7	Bullington model with LOS taper and Markus Liniger's distance correction [9 th order polynomial fit of log(path_length) to 3-edge Deygout mean]
DiffModel=8	Bullington model with LOS taper and Markus Liniger's distance correction as additive term
DiffModel=9	Bullington model with LOS taper and David Bacon's distance correction [3 point fit to 3-edge Deygout mean]



Benefits of new filtered data sets

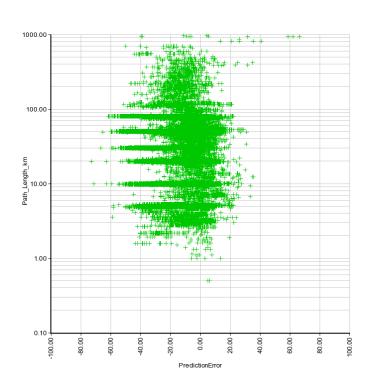
(by way of examples)



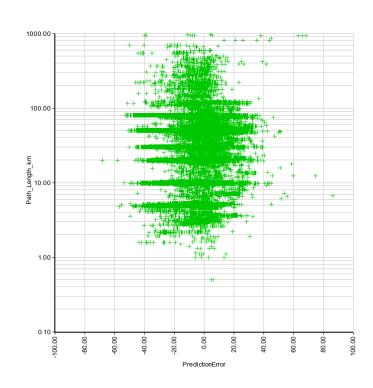
Take two models

Unfiltered data – prediction errors

- Which model is best is hard to tell - neither appears much good



Bullington Taper

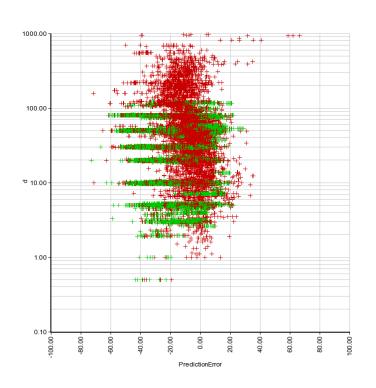


3-Edge Deygout

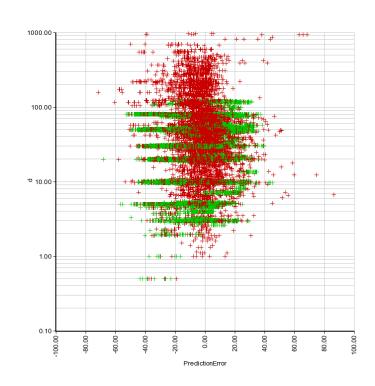


Take two models

Filtered data – now highlighting the top height measurements, those least likely to suffer terminal clutter



Bullington Taper

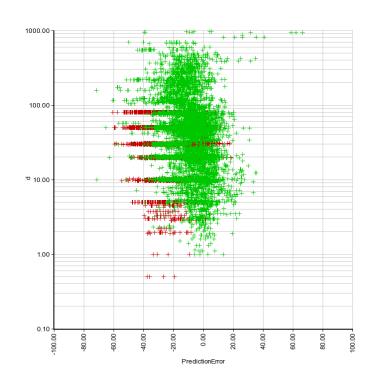


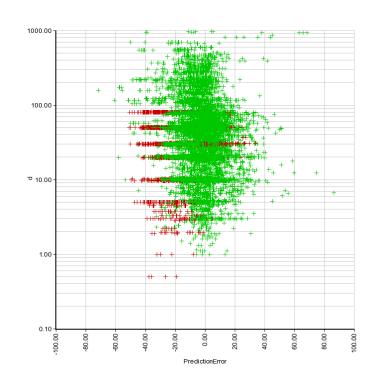
3-Edge Deygout



Take two models

Filtered data – now without height gain measurements but highlighting US Plains Data





Bullington Taper

3-Edge Deygout

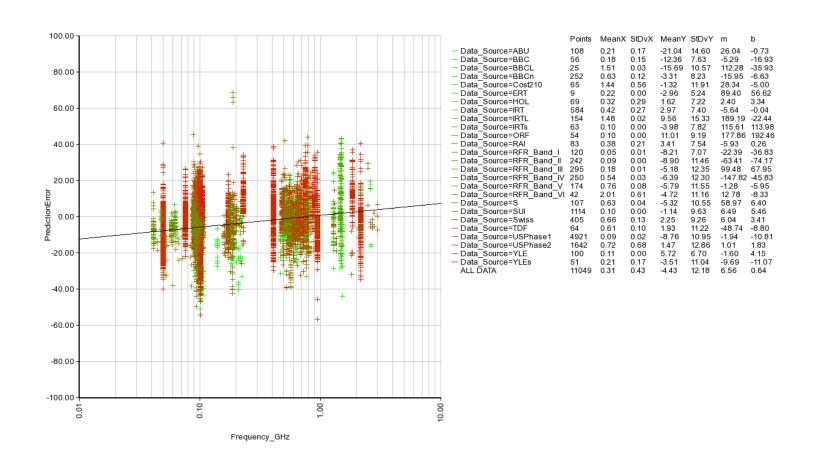
(we draw no conclusion here, but the differences are becoming clearer)



Regression fits

It is possible to make regression fits to the data

Swiss 9 point distance correction to Bullington vs frequency

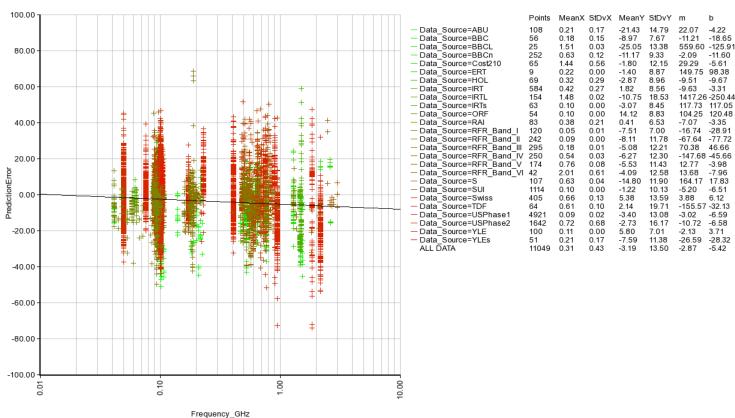




Regression fits

It is possible to make regression fits to the data

Alternative distance correction to Bullington vs frequency





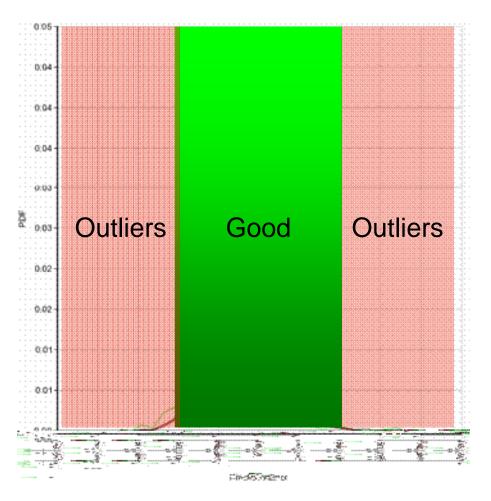
Data outliers

(From P.1812)



Outliers

Even with filtered data some measurements are still poorly predicted by P.1812



Manuallylooked at alldata more than40 dB out



Location accuracy

Some locations are not exact

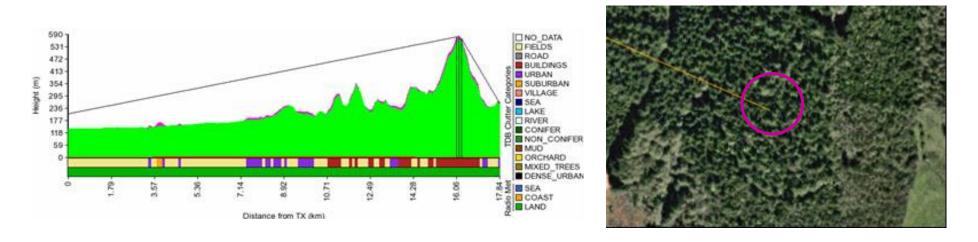


- –Is the supplied profile right?
- -We hope so but in this terrain it is very important, especially with low antennas at the receiver



Location accuracy

Here we find a 45 dB over predicted loss



Allegedly, the receiver is 1.5m above ground, just over the brow of a hill, in the middle of a forest a long way from the road.

This is unlikely – moving the receiver to the top of the hill and recalculating the profile gave a model loss within 6 dB of the measurement.



Unknown clutter

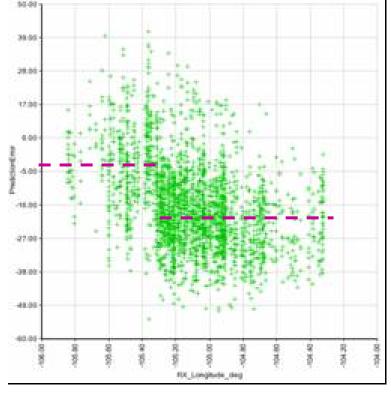
We noticed something odd with US Phase1 records

 Many of these were made at 100MHz using a 68metre tower in Boulder, Colorado.

Prediction error is a function of Longitude.

Paths into the mountains immediately to the West are predicted well.

Paths in plains to the East have 20 dB more mean loss than the model predicts.



At 50% time, this can not be a problem with the ducting h_m model We believe it is clutter loss



Unrepresented climates

Paths in the Gulf region are not well modelled

Ducting occurs for more than 50% of the time



This path measurement is 60dB higher than the prediction



What to do?

- Outliers are an issue We need to note they exist
 - If we eliminate all measurements that disagree with the model the model is bound to agree with the remaining data.
- In some cases we can eliminate the measurement:
 - Should we not test against Gulf area measurements until we have a ducting model for that climate?
 - We can eliminate paths where we know there is clutter contamination
 - but what about those we don't know about?
- For all models, the mean prediction error for some datasets appears abnormal.
 - Should we eliminate these data sets?
 - Can we equalise the means for evaluating model fit?
- Should we apply a weighting function to distinguish long term and short term measurements



Finally

The models so far for all valid data and top heights against path length

