



# GNSS time interoperability Estimation of GGTO via GNSS UTC brdc info

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#### **Context**

Each GNSS has its own time scale.

Combining measurements from different GNSS require the determination of their relative time offsets.

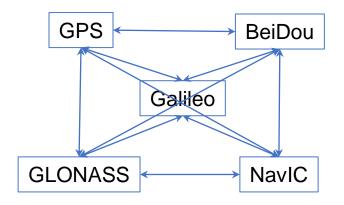
These relative time offsets can be:

- determined at user level if sufficient measurements are available
   >> this method shall always be preferred when possible because it is deemed to be more accurate
- determined using a broadcast information

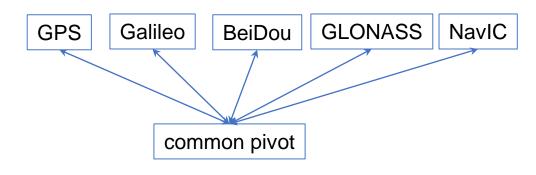


## **Possible approaches**

## The inclusion of the GNSS-to-GNSS time offset (GGTO) in the broadcast information can be envisaged with 2 approaches:



Each GNSS broadcasts its time offset wrt all the other GNSS



Each GNSS broadcasts its time offset wrt a common pivot





## **Common pivot**

#### For the common pivot, several options might be considered:

- a given GNSS time or a given UTC(k)
  - >> single point of failure : probably unacceptable
- a new time scale created externally (MGET proposal)
  - >> at least 3 drawbacks : complex, who would compute it ?, another time scale
- a new time scale created internally (xGTO proposal)
  - >> no external 3rd party, tests needed to assess perfo (see J. Hahn's presentation)
- UTCr
  - >> 10-d latency imposes extrapolation, tests needed to assess perfo
- UTC as broadcast by each GNSS
  - >> nothing additional to implement, tests needed to assess perfo



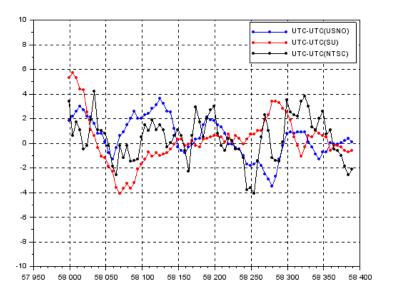
Each GNSS broadcasts an estimation of GNSST – UTC(k)

>> UTC(USNO) for GPS, UTC(SU) for GLONASS, UTCp for Galileo, UTC(NTSC) for BeiDou

Therefore this approach requires consistency of

- these estimations
- UTC(j) vs UTC(k)

UTC(k) reference time scales of GNSS are consistent with one another at  $\sim$ 2 ns (1- $\sigma$ )





- GPS broadcasts GPST UTC(USNO)
- Galileo broadcasts GST UTCp

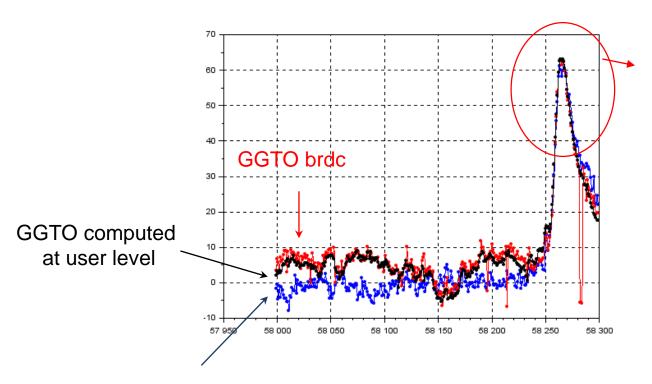
Combining these two already existing messages, one gets GST – GPST but with what level of accuracy?

#### Test of this approach:

- GPST UTC(USNO): one value per day, using the RINEX nav header of CNES station
- GST UTCp: one value per day, using the RINEX nav header of CNES station
- computation of [GST UTCp] [GPST UTC(USNO)]



Comparison from Sept. 2017 to July 2018



Drift of GST accurately reflected in the UTC-GST brdc info

no impact to users

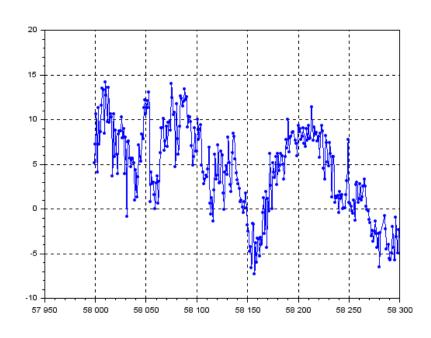
(GST - UTCp) - (GPST - UTC(USNO))





Mean = 4.4 nsStdev = 4.9 ns

Good performances even over period where GST was a bit far from UTC (because the GST – UTCp correctly reflected this)



TBC whether this performance is sufficient for interoperability



#### Conclusion

Several possible approaches to allow GNSS users to determine the GGTOs

Simple approach (investigated here) makes use of already-existing broadcast information:

- Good performance for GPS/Galileo
- To be tested with other GNSS

Required uncertainty on GGTO is TBD



## Thank you for your attention

**Questions?** 



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