



Time Transfer with Integer PPP (IPPP)

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Outline

- **■** Time transfer
- GPS CP TT : advantages of integer ambiguity resolution
- **GRG products**
- **Some results**



Time transfer: how to compare distant clocks?

- Clock trip
 - Difficult for long distances
- **■** Remote transfer : 3 basic approaches
 - One-way → GNSS Precise Point Positioning (PPP)
 - Common-view
 - Two-way



GPS carrier phase time transfer

- Decisive advantage of GPS carrier phase observables : lower noise
 - ... but some drawbacks:
 - Ambiguous
 - Sensitive to the model precision (frequency bias or drift)
 - Discontinuities at day boundaries
- Taking into account the integer nature of the ambiguities allows to overcome most of these problems



How to handle day-boundary discontinuities?

- processing of longer batches
 - reports the problem to boundaries of batches
- continuous processing
 - heavy and some errors effects may accumulate, e.g. [Dach, 03]
- concatenation using overlapping series, e.g. [Bruyninx, 99] or [Larson, 00] ♦ addition of a random-walk noise component, limitation of the long-term stability
- **sliding window,** e.g. [Guyennon, 07]
 - minimize rather than solve the problem
- more sophisticated methods [Dach, 04] : clock handover and ambiguity stacking
 - when many internal parameters must be kept with each individual daily solution to compute a continuous clock solution (normal equations and ambiguities of the overlapping passes)
 - ⇒ not usable by external users who have access only to the daily ephemeris and clocks



Integer ambiguity advantages

- Phase clock solutions are ambiguous and need to be aligned on the code for time transfer
 - Alignment on code by 1-day batches may create boundary discontinuities due to code noise
 - For integer ambiguities solutions, such discontinuities are integer numbers of λ_c and can be easily cancelled out



Ambiguity fixing method (1/2)

- Ambiguities fixed directly on the zero-difference phase measurements
 - Clocks and all parameters are solved for simultaneously with the ambiguity fixing

■ Step 1 : Wide-lane

- Fix the widelane ambiguity (ambiguity associated to L2-L1), using the 4-observable Melbourne-Wübbena combination
- ⇒ Fixing at pre-processing level using only the receiver measurements and a set of satellite biases (Wide-lane Satellite Biases, WSB), available on GRG ftp-site (grgxxxxx.wsb, daily update)

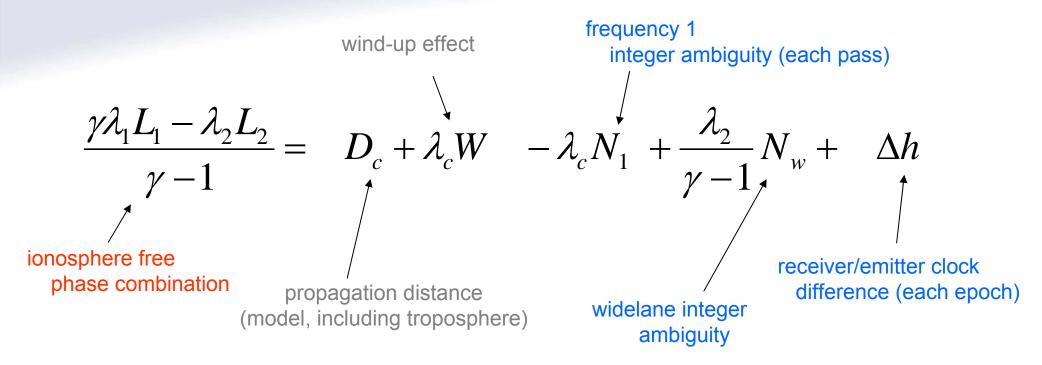
■ Step 2 : Narrow-lane

- Use of iono-free code and phase combinations
- Remaining ambiguity associated to an equivalent λ of 10.7 cm = Narrow-lane ambiguity
- * This ambiguity fixing is performed at zero-difference level, using the complete models and parameterization (orbits, stations coordinates, clocks...). Narrow-lane ambiguity are fixed using a bootstrap method applied on the normal equations constructed with the floating solution
- Number of ambiguities to solve for is typically 7000, and more than 95% of the phase measurements have a fixed ambiguity at the end of the process



Ambiguity fixing method (2/2)

Zero-difference iono-free phase equation



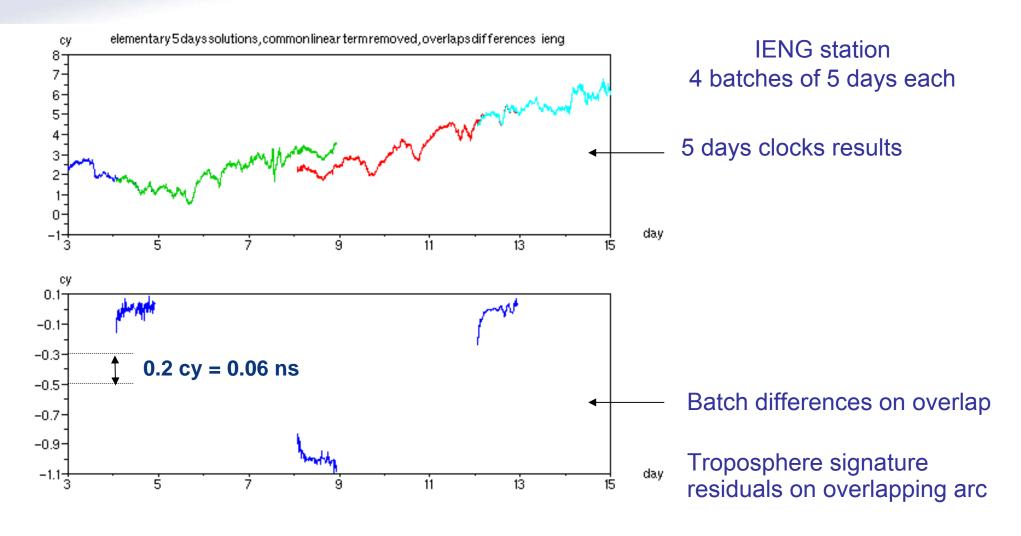
Floating solutions: direct identification of floating ambiguities (equivalent wavelength of the N_1 , N_2 integer problem is too small)

Integer solution : 1st step = separate integer N_w identification 2nd step = iono-free phase solution with integer N_1 (λ_c = 10.7 cm)



Day-boundary discontinuities

■ Receiver clock differences are defined up to an overall unknown number of cycles





GRG products

- GRG = new IGS Analysis Center since May 2010, CNES-CLS joint effort
- **■** GRG products :
 - based upon processing of a global network of GPS stations
 - integer ambiguity resolution applied (identification of wide-lane satellite biases : WSB, called grgxxxxx.wsb)
 - ► This allows to perform IPPP (PPP with integer ambiguity resolution) that provides continuous receiver clock solutions between two successive batches
- See: <u>www.igsac-cnes.cls.fr</u>

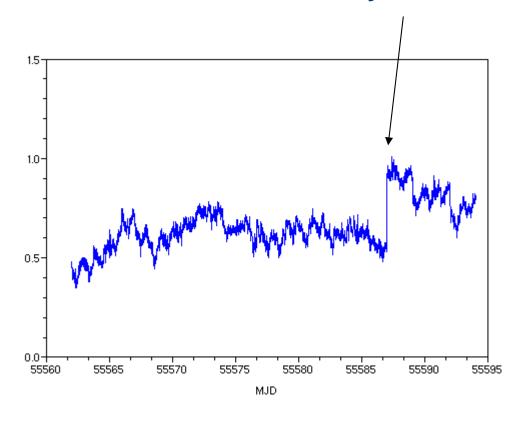


Results on KRIS/NICT

Differences between GPSPPP (floating PPP) and IPPP (in ns)

std = 0.08 ns
(computed before the
 discontinuity)

Batch-boundary discontinuity in GPSPPP





Conclusions

- GRG products allows IPPP that provide continuous GPS CP TT, for instance with GINS software package
- IPPP results compared to TWSTFT and GPSPPP
 - Agreement with GPSPPP: STDEV = 0.08 ns
 GPSPPP batch-boundary discontinuities overlooked (these discontinuities have a median value of ~ 0.2 ns)
 - Agreement with TWSTFT : STDEV = 0.3 ns
- Long term consistencies and code/phase biases to be further investigated
- **■** Extension to other GNSS in progress